

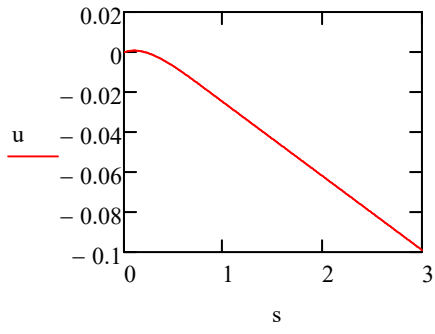
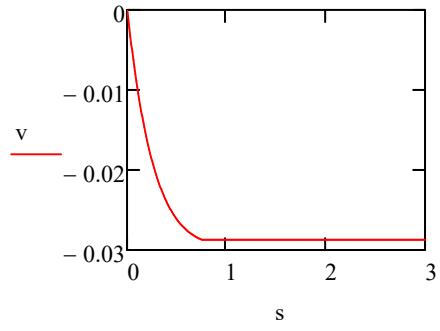
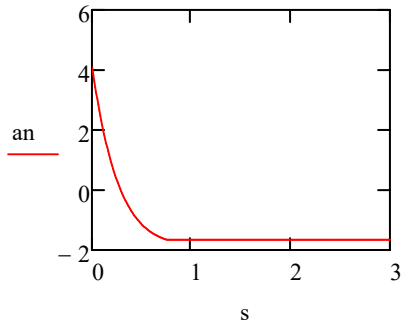

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for m=1:n1
    p(m)=0.0;
end;
jk1=jk+1;
for n=1:jk1;
    t=(n-1)*dt;
    p(n)=450000*(1-t/td)*exp(-2.0*t/td);
end;
an(1)=(p(1)-c*v(1)-k*u(1))/ma;
kh=k+3.0*c/(theta*dt)+6.0*ma/(theta*dt)^2;
a=6.0*ma/(theta*dt)+3.0*c;
b=3.0*ma+theta*dt*c/2.0;
for i=1:n1;
    s(i)=(i-1)*dt;
end;
for i=2:n1;
    ww=(p(i)-p(i-1))*theta+a*v(i-1)+b*an(i-1);
    xx=ww/kh;
    zz=(6.0*xx/((theta*dt)^2)-6.0*v(i-1)/(theta*dt)-3.0*an(i-1))/theta;
    yy=dt*an(i-1)+dt*zz/2.0;
    v(i)=v(i-1)+yy;
    an(i)=an(i-1)+zz;
    vv=dt*v(i-1)+dt*dt*(3.0*an(i-1)+zz)/6.0;
    u(i)=u(i-1)+vv;
end;
figure(1);
    plot(s,u);
    xlabel(' time (t) in seconds')
    ylabel(' Response displacement u in m')
    title(' dynamic response')

```

$$\begin{pmatrix} p \\ u \end{pmatrix}$$

$\left. \begin{array}{l} v \\ an \\ s \end{array} \right\} := \text{SolveProblem}(dt)$



Input independent variables to define the problem

$$m_a := 110000$$

$$k := 10075582$$

$$\theta := 1.42$$

$$r := 0.07$$

$$t_t := 3.0$$

$$n := 300$$

$$t_d := 0.75$$

$$u_n := 0$$

These could be set here or in the program to all zeroes to commence

$$v_n := 0$$

$$a_n := 0$$

Calculate variables

$$c_n := 2 \cdot r \cdot \sqrt{k \cdot m_a}$$

$$n_1 := n + 1$$

$$dt_n := \frac{t_t}{n}$$

$$jk := \frac{td}{dt} \quad jk = 75$$

$$jk1 := jk + 1$$

Do the iteration

```
SolveProblem(dt) :=
  p_n ← 0
  an_n ← 0
  u_n ← 0
  v_n ← 0
  for i ∈ 0..jk
    t ← i·dt
    p_i ← 450000 · (1 - t/td) · e-2·t/td
    an_0 ← (p_0 - c·v_0 - k·u_0) / ma
    kh ← k + 3.0·c / (θ·dt) + 6.0·ma / (θ·dt)2
    a ← 6.0·ma / (θ·dt) + 3.0·c
    b ← 3.0·ma + (θ·dt·c) / 2.0
    for i ∈ 0..n
      s_i ← i·dt
    for i ∈ 1..n
      ww ← (p_i - p_{i-1})·θ + a·v_i + (b·an_i) / θ
      xx ← ww / kh
      zz ← [6.0·xx / (θ·dt)2] - (6.0·v_i) / (θ·dt) - (3.0·an_i) / θ
      yy ← dt·an_i + (dt·zz) / 2.0
      v_i ← v_{i-1} + yy
      an_i ← an_{i-1} + zz
      vv ← dt·v_i + (dt·dt·(3.0·an_i + zz)) / 6.0
      u_i ← u_{i-1} + vv
  ( p )   ( p )
```

(i-1))/theta;

$$\begin{pmatrix} u \\ v \\ an \\ s \end{pmatrix} \leftarrow \begin{pmatrix} u \\ v \\ an \\ s \end{pmatrix}$$