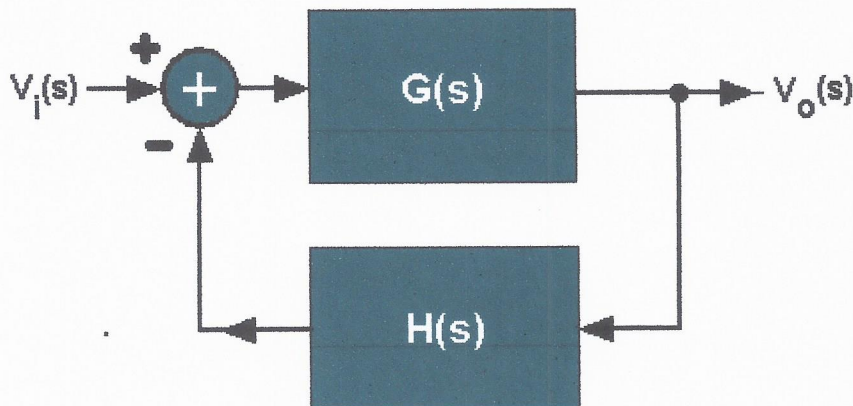


Nichols Chart

Consider a generic L.T.I. feedback system here below depicted:



as known, the transfer function is:

$$G_{fNch}(j \cdot \omega) = \frac{V_o(j \cdot \omega)}{V_i(j \cdot \omega)} = \frac{G_{Nch}(j \cdot \omega)}{1 + G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)}$$

The following products be represented in exponential forms

$$G_{fNch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega) = M_{Nch} \cdot e^{j \cdot \phi}$$

$$\text{open loop gain: } G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega) = Q_{Nch} \cdot e^{j \cdot \alpha}$$

it follows that:

$$G_{fNch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega) = \frac{G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)}{1 + G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)} = \frac{Q_{Nch} \cdot e^{j \cdot \alpha}}{1 + Q_{Nch} \cdot e^{j \cdot \alpha}}$$

$$Q_{Nch} = |G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)|$$

hence must be worth the equality:

$$M_{Nch} \cdot e^{j \cdot \phi} = \frac{Q_{Nch} \cdot e^{j \cdot \alpha}}{1 + Q_{Nch} \cdot e^{j \cdot \alpha}}$$

In addition put:

$$M_{dB} = 20 \cdot \log(|G_{fNch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)|) = 20 \cdot \log\left(\left|\frac{G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)}{1 + G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)}\right|\right)$$

or rather:

$$M_{dB} = 20 \cdot \log \left[\frac{Q_{Nch}}{\sqrt{(Q_{Nch} \cdot \cos(\alpha) + 1)^2 + (Q_{Nch} \cdot \sin(\alpha))^2}} \right] \quad \phi = \arg \left(\frac{G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)}{1 + G_{Nch}(j \cdot \omega) \cdot H_{Nch}(j \cdot \omega)} \right)$$

inverting:

$$10^{\frac{M_{dB}}{20}} = \frac{Q_{Nch}}{\sqrt{(Q_{Nch} \cdot \cos(\alpha) + 1)^2 + (Q_{Nch} \cdot \sin(\alpha))^2}}$$

placing $K = 10^{\frac{M_{dB}}{20}}$ can write $K = \frac{Q_{Nch}}{\sqrt{(Q_{Nch} \cdot \cos(\alpha) + 1)^2 + (Q_{Nch} \cdot \sin(\alpha))^2}}$

$$K^2 = \frac{Q_{Nch}^2}{(Q_{Nch} \cdot \cos(\alpha) + 1)^2 + (Q_{Nch} \cdot \sin(\alpha))^2}$$

which is a quadratic equation with constant coefficients in the unknown Q_{Nch} .

Results that (representing Q_{Nch} in dB):

$$Q_{Nch}(\alpha, M_{dB}) := 20 \cdot \log \left[\begin{array}{l} 10^{\frac{M_{dB}}{20}} \cdot \frac{-\cos(\alpha) \cdot 10^{\frac{M_{dB}}{20}} + \sqrt{1 - \left(10^{\frac{M_{dB}}{20}}\right)^2 \cdot \sin(\alpha)^2}}{\left(10^{\frac{M_{dB}}{20}}\right)^2 - 1} \\ -10^{\frac{M_{dB}}{20}} \cdot \frac{\cos(\alpha) \cdot 10^{\frac{M_{dB}}{20}} + \sqrt{1 - \left(10^{\frac{M_{dB}}{20}}\right)^2 \cdot \sin(\alpha)^2}}{\left(10^{\frac{M_{dB}}{20}}\right)^2 - 1} \end{array} \right]$$

Moreover, expanding the following relation

$$\frac{Q_{Nch} \cdot e^{j\alpha}}{1 + Q_{Nch} \cdot e^{j\alpha}} = \frac{Q_{Nch} \cdot (Q_{Nch} + \cos(\alpha) + j \cdot \sin(\alpha))}{Q_{Nch}^2 + 2 \cdot \cos(\alpha) \cdot Q_{Nch} + 1} = M \cdot e^{j\phi}$$

results: $M \cdot e^{j\phi} = M \cdot (\cos(\phi) + j \cdot \sin(\phi)) = M \cdot \cos(\phi) \cdot \left(1 + j \cdot \frac{\sin(\phi)}{\cos(\phi)}\right)$

or even $M \cdot \cos(\phi) \cdot (1 + j \cdot \tan(\phi)) = \frac{Q_{Nch} \cdot (Q_{Nch} + \cos(\alpha) + j \cdot \sin(\alpha))}{Q_{Nch}^2 + 2 \cdot \cos(\alpha) \cdot Q_{Nch} + 1}$

so that:
$$M \cdot \cos(\phi) \cdot (1 + j \cdot \tan(\phi)) = \frac{Q_{Nch} \cdot (Q_{Nch} + \cos(\alpha)) \cdot \left[1 + j \cdot \frac{\sin(\alpha)}{(Q_{Nch} + \cos(\alpha))} \right]}{Q_{Nch}^2 + 2 \cdot \cos(\alpha) \cdot Q_{Nch} + 1}$$

Follows from this that:

$$\tan(\phi) = \frac{\sin(\alpha)}{Q_{Nch} + \cos(\alpha)} \quad M \cdot \cos(\phi) = \frac{Q_{Nch} \cdot (Q_{Nch} + \cos(\alpha))}{Q_{Nch}^2 + 2 \cdot \cos(\alpha) \cdot Q_{Nch} + 1}$$

solving the first one respect to Q_{Nch} , you get:

$$Q_{Nch}(\alpha, \phi) = \frac{\sin(\alpha)}{\tan(\phi)} - \cos(\alpha) = \frac{\sin(\alpha - \phi)}{\sin(\phi)}$$

$$A_{Nch}(\alpha, \phi) = 20 \cdot \log(Q_{Nch}(\alpha, \phi)) \quad \alpha(\phi, Q_{Nch}) := \phi + \arcsin(Q_{Nch} \cdot \sin(\phi))$$

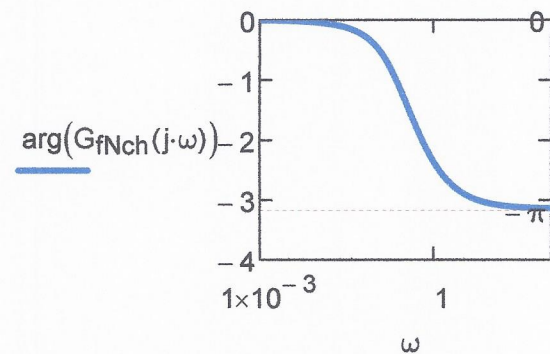
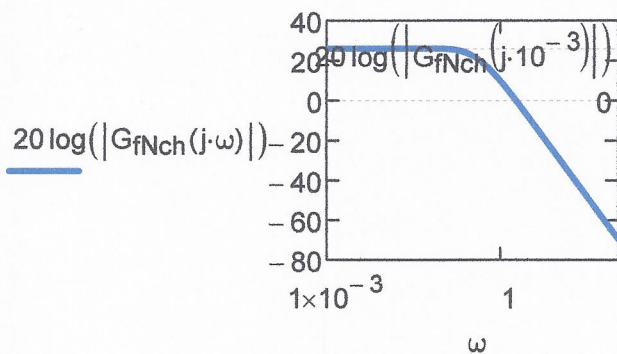
$$A_{Nch}(\alpha, \phi) = 20 \cdot \log \left[\frac{-(\tan(\phi) \cdot \cos(\alpha) - \sin(\alpha))}{\tan(\phi)} \right]$$

and ultimately:
$$A_{Nch}(\alpha, \phi) := 20 \cdot \log[\sin(\alpha) \cdot (\cot(\phi) - \cot(\alpha))] \quad \tan(\phi) < \tan(\alpha)$$

About the Nichols Chart, it is noted that in abscissa there is the angle α while in ordinate there are $Q_{Nch}(\alpha, \text{MdB})$ in dB and $A_{Nch}(\alpha, \phi)$. The graph then shows two families of curves, one with parameter MdB : the other with parameter ϕ .

Example:
$$G_{fNch}(s) := \frac{20 \cdot (1 + s \cdot 8)}{(1 + s \cdot 2) \cdot (1 + s \cdot 4) \cdot (1 + s \cdot 6)} \quad (|G_{fNch}(j\omega)|_{\text{dB}} \text{ blue line})$$

Bode plots:

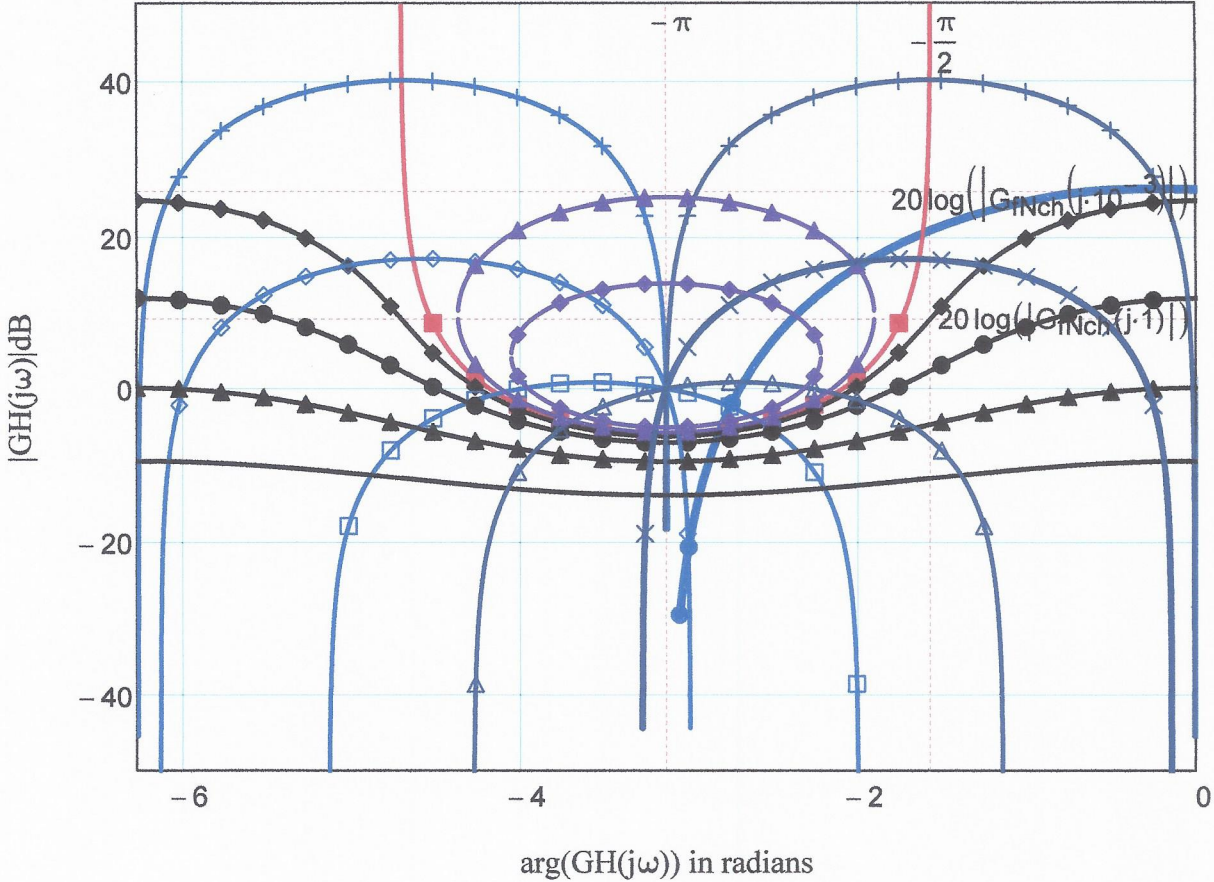


$$\underline{m} := 2 \quad \underline{\alpha} := -\pi \cdot m, -\pi \cdot m + \frac{2 \cdot \pi \cdot m}{10000} .. \pi \cdot m$$

$Q_{Nch}(\alpha, \text{MdB})$ MdB is a parameter $A_{Nch}(\alpha, \phi)$ ϕ is a parameter

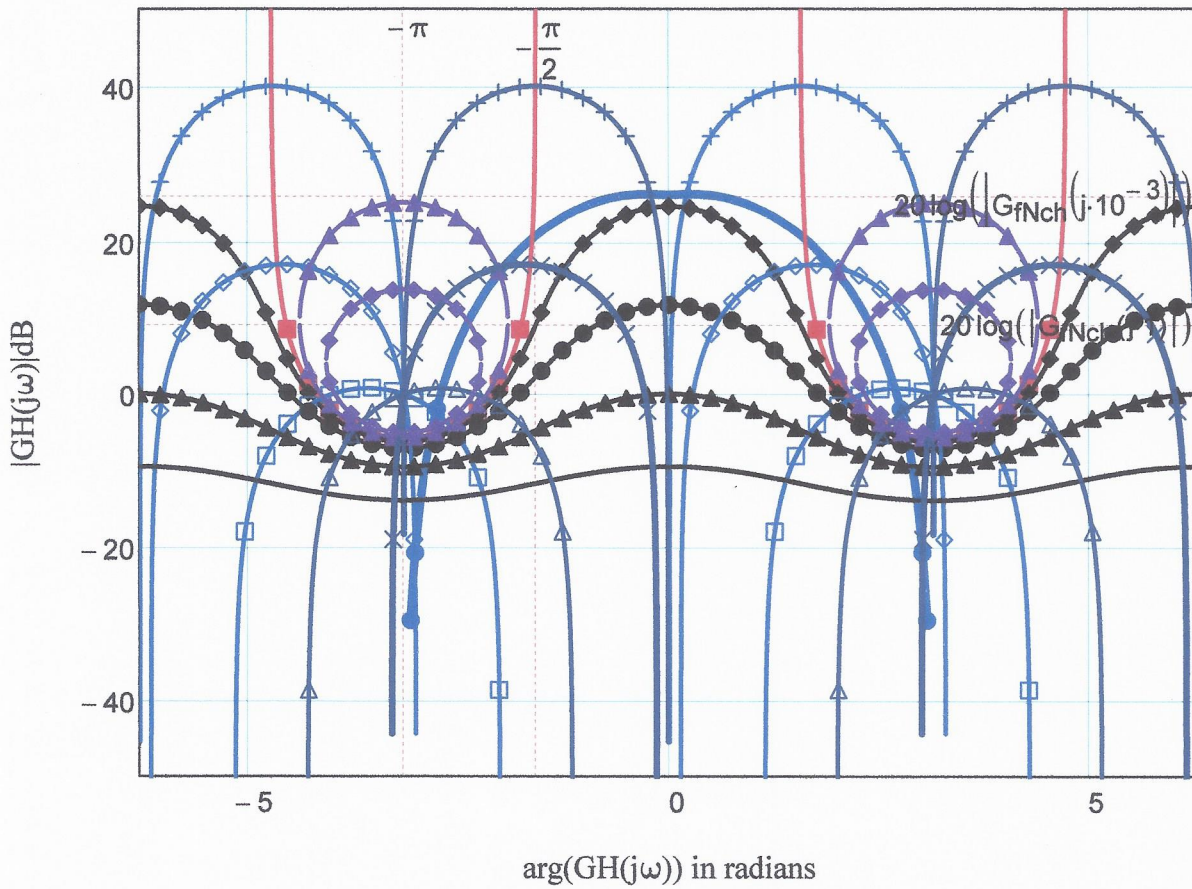
From the observation of the graph, can be deduced the values of the *gain margin* and the *phase margin* and therefore have a measure of the degree of stability of the system with feedback.

Nichols Chart



- |G.f(jω)|dB vs arg(GH(jω))
- M.dB=0
- + + + φ=0.01
- ◆◆◆ M.dB=-0.5
- φ=-2
- M.dB=-2
- ◇◇◇ φ=-3
- ▲▲▲ M.dB=-6
- + + + φ=-0.01
- M.dB=-12
- △△△ φ=2
- ▲▲▲ M.dB=0.5
- ▲▲▲ M.dB=0.5
- ××× φ=3
- ◆◆◆ M.dB=2.0
- ◆◆◆ M.dB=2.0

Nichols Chart



- $|G.f(j\omega)|$ dB vs $\arg(GH(j\omega))$
- M.dB=0
- + + + $\phi=0.01$
- ◆◆◆ M.dB=-0.5
- $\phi=-2$
- M.dB=-2
- ◇◇◇ $\phi=-3$
- ▲▲▲ M.dB=-6
- + + + $\phi=-0.01$
- M.dB=-12
- △△△ $\phi=2$
- ▲▲▲ M.dB=0.5
- ▲▲▲ M.dB=0.5
- ××× $\phi=3$
- ◆◆◆ M.dB=2.0
- ◆◆◆ M.dB=2.0